

# SOHAIB KAIMALI

Montreal, Canada | [sohaib.kaimali@mail.mcgill.ca](mailto:sohaib.kaimali@mail.mcgill.ca) | [linkedin.com/in/sohaib-kaimali](https://linkedin.com/in/sohaib-kaimali) | [kaimalisoahib.github.io/](https://kaimalisoahib.github.io/)

## EDUCATION

**McGill University** Montreal, QC  
*B.Eng. in Computer Engineering* Sept. 2025

## PROFESSIONAL EXPERIENCE

**Software Engineer Consultant Intern** Remote  
*MotionCorrect, Inc.* Jun. 2022 – Present

- Architected full-stack browser extensions (Chrome/Firefox) with a **Rust** backend and a performant vanilla JS frontend.
- Optimized **CI/CD** pipelines, reducing build times by **80%** (2 hrs to 20 mins) via caching and job parallelization.
- Automated Git workflows and led code reviews to improve development velocity and reduce post-deployment bugs.

**McGill Robotics AUV Design Team** Montreal, QC  
*Software Team Member* Sept. 2025 – Present

- Engineered a vision pipeline using **YOLO** models and **ZED SDK** to transform 2D detections into accurate 3D coordinates, implementing filtering logic + EKF to generate a stable object map for real-time mission planning.
- Developed the **state estimation** and control systems, fusing DVL, IMU, and VIO data via an **EKF** for odometry and implementing **PID/quaternion** controllers driven by a behaviour tree (**PyTree**) logic for autonomous navigation.
- Designed a **Unity simulation** environment connected to the **ROS 2** codebase via **TCP**, streaming synthetic sensor data and video feeds to validate the full autonomy stack.

**FIRST Robotics Team 3986 - Express-O** Montreal, QC  
*Robotics Software Lead & Drive Team Captain* Jan. 2020 – Jun. 2022

- Engineered the robot's software for reliable autonomous maneuvers, creating a **computer vision** system (**OpenCV**) for localization and a **PID/feedforward controller** that boosted motor precision by 20%.
- As Captain, led the team to a 2022 Montreal Regional victory and World Championship qualification; secured \$7,000+ in grants for leadership in STEM outreach.

**Vanier College** Montreal, QC  
*Teaching Assistant* Aug. 2023 – Dec. 2023

- Mentored 30+ students per semester in mechanics, developing problem-solving frameworks and troubleshooting.

## TECHNICAL PROJECTS

**Hackathon Achievements** | [Devpost](#) 3× First Place & 2× Second Place

**Heart Disease Prediction Model** | [GitHub](#) *Python, Scikit-learn, ONNX, Data Science*

- Led end-to-end data science research using **machine learning** to build a predictive model (logistic regression); solved class imbalance and deployed it for client-side inference with **ONNX**.

**GPU-Accelerated Network Simulation** | [GitHub](#) *Java, OpenGL, GLSL, Compute Shaders*

- Created a real-time, agent-based simulation of emergent behavior, parallelized on the **GPU** with **compute shaders** to procedurally generate bio-inspired networks for pathfinding and statistical analysis.

**Independent Study: Deep Reinforcement Learning** | [Hugging Face Course](#) *Python, DQN, PPO*

- Completed a self-directed Deep RL course (theory + hands-on notebooks) and studied core algorithms including DQN and PPO. [Course Repo](#)
- Implemented and trained agents in toy control environments; evaluated learning stability using reward curves and rollout performance.

**Sign Atlas: Deep Learning for ASL** | [GitHub](#) *Next.js, TensorFlow.js, MediaPipe*

- Won 1st place at DawHacks by building an AI tutor that uses a custom **deep learning model** (**MediaPipe**) for real-time **gesture recognition**, creating an interactive learning feedback loop.

## TECHNICAL SKILLS

**Languages:** Python, C/C++, C#, Rust, Java, JavaScript/TypeScript, Shell, GLSL, SQL

**AI & Data Science:** Machine Learning, Deep Learning, Modeling, Scikit-learn, TensorFlow, PyTorch, Pandas, Numpy

**Software & Robotics:** Git, Docker, CI/CD, AWS, REST APIs, CUDA, Isaac Sim, ROS 2, Unity, PID Control, ESP32