# SOHAIB KAIDALI

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#### **EDUCATION**

McGill University

Montreal, QC

B.Eng. in Computer Engineering

Aug. 2025 - Dec. 2028

#### PROFESSIONAL EXPERIENCE

MotionCorrect, Inc.

Remote

Junior Software Development Consultant

Jun. 2022 - Present

- Developed and maintained full-stack, cross-browser extensions (Chrome MV3/Firefox MV2), using Rust for backend logic and performant, vanilla JavaScript for data-driven, interactive frontends.
- Reduced CI/CD build times by over 80% (2 hrs to 20 mins) by optimizing build caching, parallelizing jobs, and refactoring complex deployment scripts for Windows, macOS, and Linux.
- Increased development velocity and reliability by automating Git workflows and conducting detailed code reviews, helping in reducing post-deployment bugs in a remote-first environment.

Vanier College Montreal, QC

Mechanics Laboratory Assistant

Aug. 2023 - Dec 2023

• Mentored 30+ students per semester in mechanics labs, improving comprehension of core concepts by developing structured problem-solving frameworks and troubleshooting technical challenges.

# FIRST Robotics Team 3986 - Express-O

Montreal, QC

Captain, Pilot, and Lead Developer

Jan. 2020 - Jun. 2022

- Engineered an advanced motor control system with PID and feedforward control, achieving a 20% precision boost, high stability, and responsive control under variable loads.
- Deployed a robust computer vision localization pipeline using OpenCV to fuse camera data with odometry, enhancing real-time navigation accuracy for reliable execution of complex autonomous maneuvers.
- Led team to victory in the 2023 Montreal Regional Championship, qualifying for the FIRST World Championship.
- Secured annual \$5,000 grant from the Montreal Mayor's Office and earned the Fusion Jeunesse Leaders MTL Scholarship (\$2,000) for leadership in advancing STEM education.

## SELECTED PROJECTS

Hackathon Achievements |  $\underline{\text{Devpost}}$  3× First Place & 2× Podium Finishes in collaborative, rapid prototyping events Heart Disease Prediction Model |  $\underline{\text{GitHub}}$  Python, Scikit-learn, ONNX, Data Science

• Led end-to-end data science research using statistical techniques and machine learning to build a predictive model (logistic regression); solved class imbalance and deployed it for client-side inference with ONNX.

### GPU-Accelerated Network Simulation | GitHub

Java, OpenGL, GLSL, Compute Shaders

• Created a real-time, agent-based simulation of emergent behavior, parallelized on the GPU with compute shaders to procedurally generate bio-inspired networks for pathfinding and statistical analysis.

#### Rubber Duck Sumo Robot | GitHub

C++, ESP32, PID,  $I^2C$ , ToF Sensors

• Built an autonomous robot with a 5-ToF sensor array and dynamic, fault-tolerant I<sup>2</sup>C bus-recovery, feeding a robust, PID-controlled finite state machine (FSM) that achieved 1.7 m/s pushes.

# Sign Atlas: Deep Learning for ASL | GitHub

Next.js, TensorFlow.js, MediaPipe

• Won 1st place at DawHacks by building an AI tutor that uses a custom deep learning model (MediaPipe) for real-time gesture recognition, creating an interactive learning feedback loop.

### TECHNICAL SKILLS

Languages: Python, C/C++, Rust, Java, JavaScript/TypeScript, Shell, GLSL, SQL

AI & Data Science: Machine Learning, Deep Learning, Modeling, Scikit-learn, TensorFlow, PyTorch, Pandas, XAI Software & Robotics: Git, Docker, CI/CD, REST APIs, Web Sockets, Databases, ROS2, Unity, PID Control, ESP32, I<sup>2</sup>C